



Annex O – MSC – MILITARY VEHICLE SIMULATION WITH ADAMS: MOBILITY AND BEYOND

Note: This Annex appears in its original format.

STO-TM-AVT-308 O - i





O - ii STO-TM-AVT-308





Military Vehicle Simulation with Adams Mobility and Beyond

Presentation For NG-NRMM CDT AVT 308

Eric Pesheck, PhD, USA

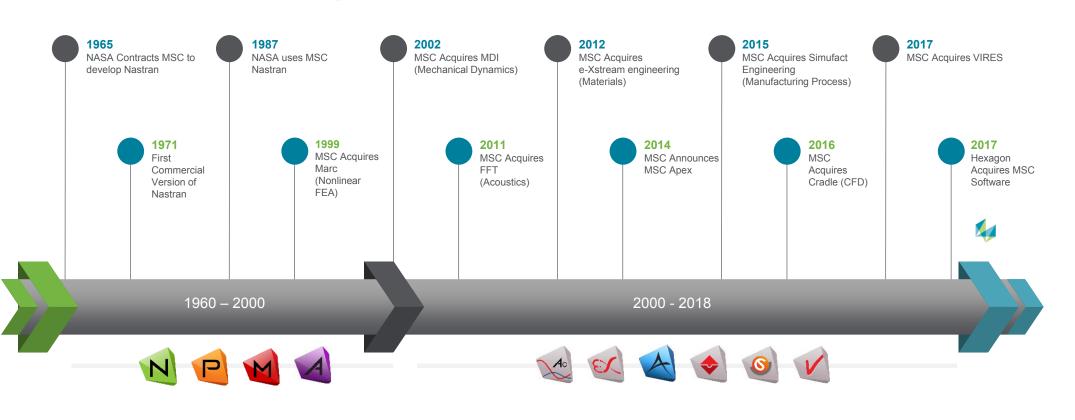




SCIENCE AND TECHNOLOGY ORGANIZATION COLLABORATION SUPPORT OFFICE



MSC Software 50 Years of CAE



- 1300 Employees in 35 Offices
- Annual Revenue ~\$230 million

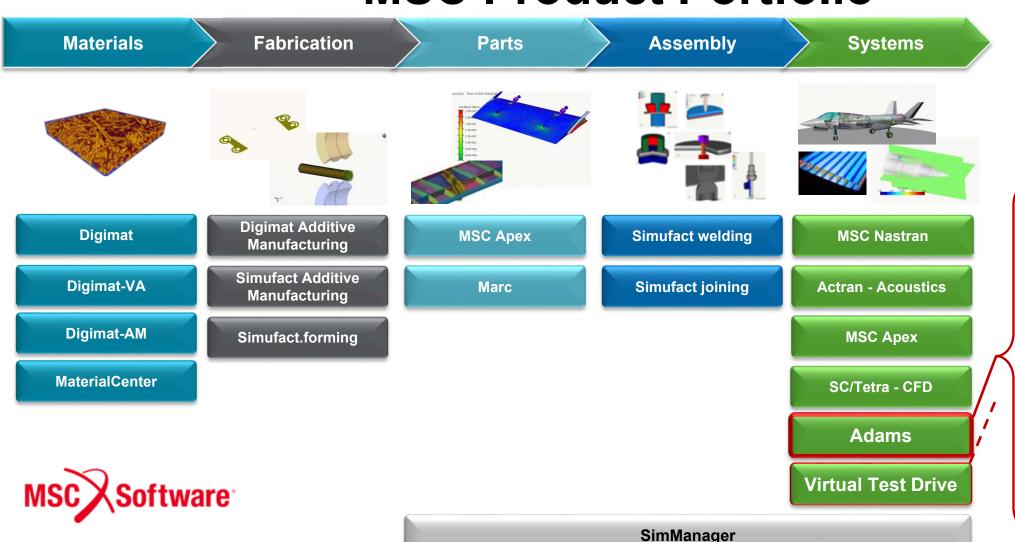


Virtually every auto, aero & heavy machinery OEM is a customer

SCIENCE AND TECHNOLOGY ORGANIZATION COLLABORATION SUPPORT OFFICE



MSC Product Portfolio

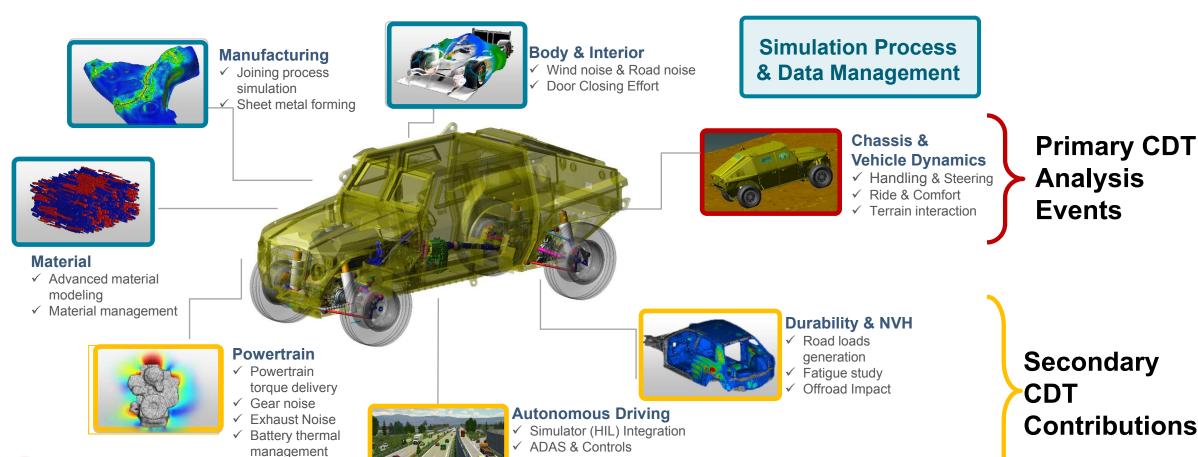


- **NG-NRMM** work has used the Adams product portfolio.
- Work performed by **MSC Consulting** services organization
- **Real-Time model** leveraged for VTD





MSC Vehicle Solutions



Contributions

STO-TM-AVT-308 SLIDE 4

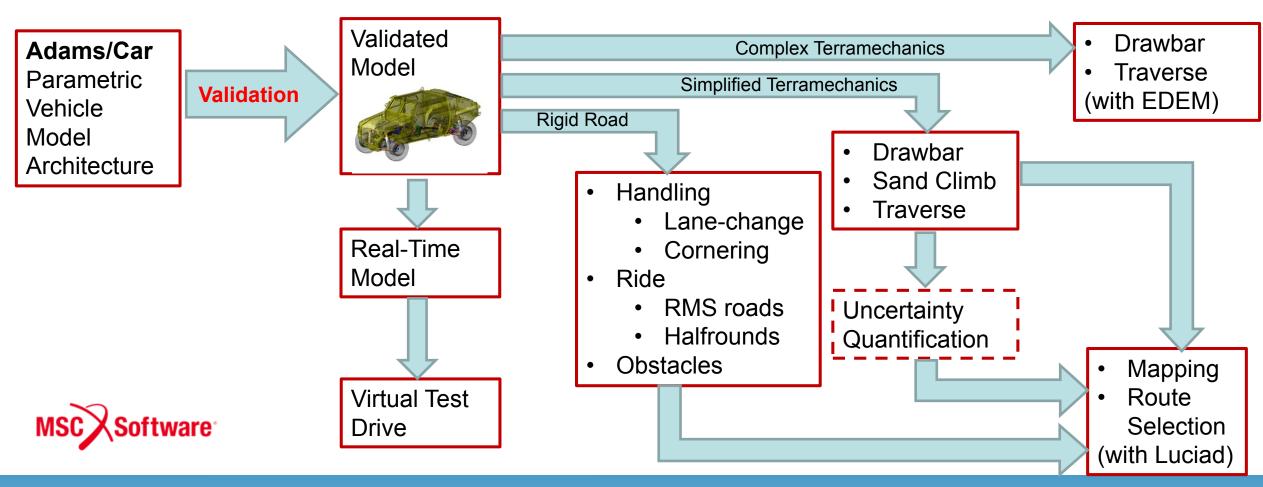
Perception & validation

evaluation





MSC AVT-308 Activities - Overview







Rigid Road Events

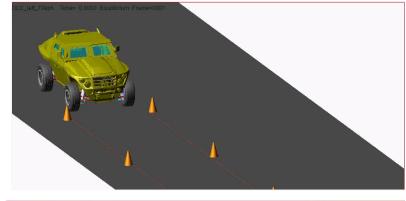
Events

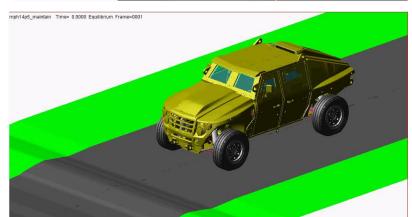
- Double LaneChange
- Cornering
- Halfrounds
- RMS courses
- V-Ditch
- Step Climb
- Acceleration
- Braking
- Grade Climb
- Side Slope

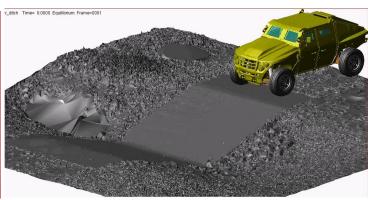
Methods

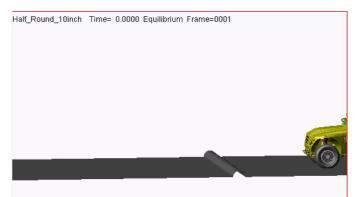
- DriverStrategies
- Tire fidelity
- Detailed driveline
- Specialized dampers
- RoadContactModels

Results













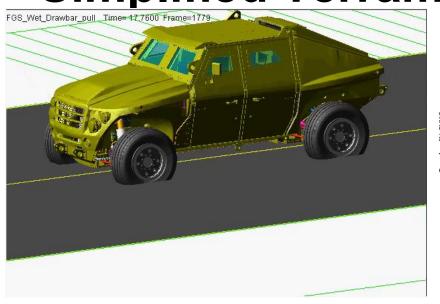
Simplified Terramechanics

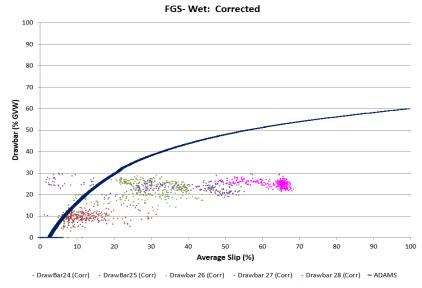
Events

- Drawbar
- Hill Climb
- UQ DOEs
- Traverse

Methods

- Bekker-Wong Soft road
- Scripting
- Scanned mesh roads













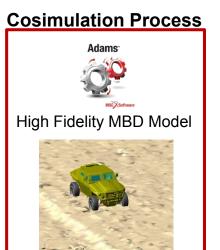
Complex Terramechanics

Events

- Calibration
- Drawbar
- Traverse

Methods

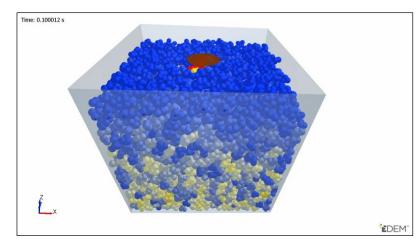
- EDEMConfiguration
- Soil Bed Preperation
- Cosimulation

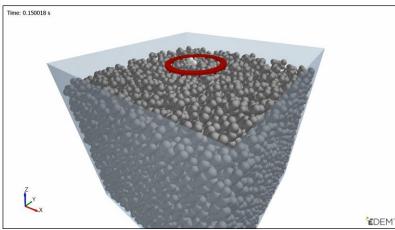






Results

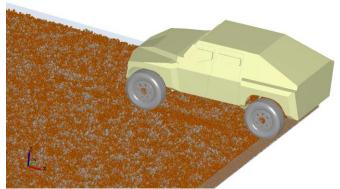




Time: 0.600045 s

Traverse: Sand Bed Cornering and Acceleration





EDEM"



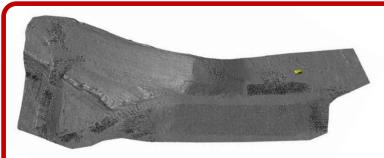


Adams Real-Time / Virtual Test Drive integration

Export Real-Time model



Create VTD 3D vehicle model



Publish KRC terrain for VTD scenario



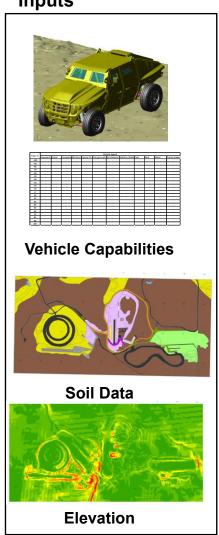
VTD runs Adams vehicle plant (Different Vehicle and scenario shown)





Applying Modern Mapping Frameworks

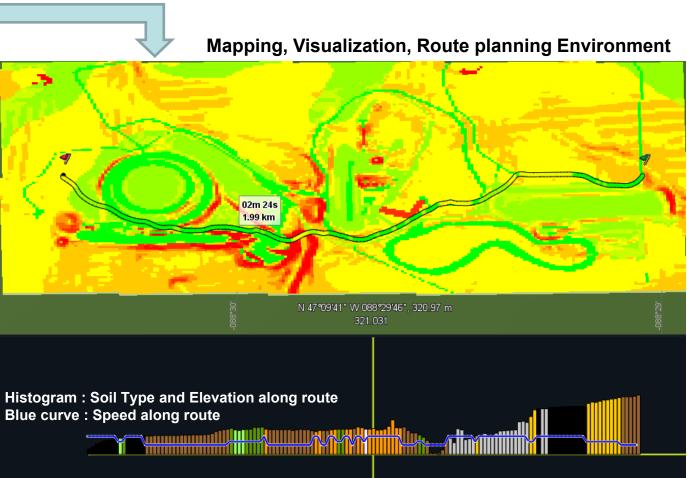
Inputs





- Custom App in Lucy Framework
- **Custom Map Layers**
- Generate Go/No-Go
- **Custom Routing** Algorithm

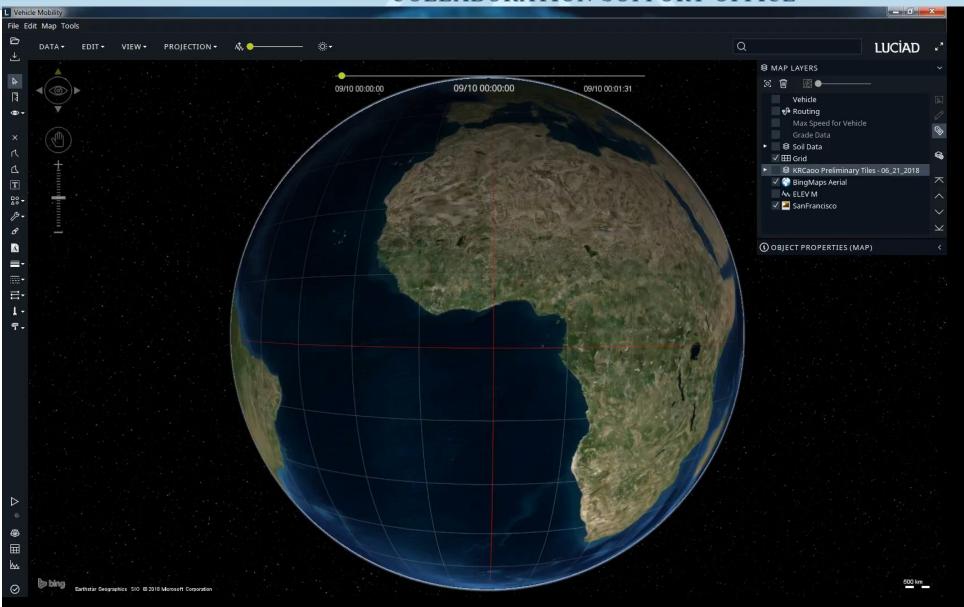






SCIENCE AND TECHNOLOGY ORGANIZATION COLLABORATION SUPPORT OFFICE









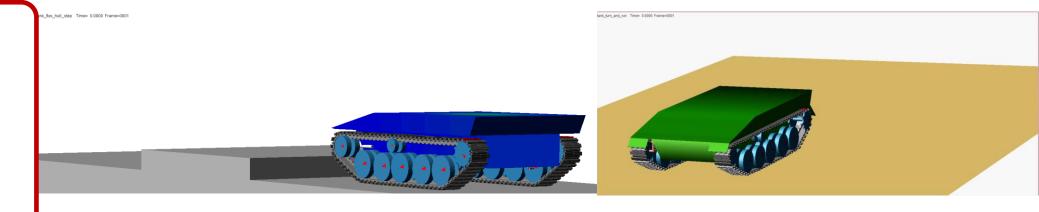
What About Tracks?



Adams Tracked Vehicle (ATV) toolkit

ank save Time= 0.0000 Frame=0001

- Detailed track modeling
- Rigid or soft-soil ground
- Automated track wrapping
- Extensible template-based approach
- Global user-base:
 - Defense
 - Construction
 - > Sport





What Next?

SCIENCE AND TECHNOLOGY ORGANIZATION COLLABORATION SUPPORT OFFICE



Continuous Improvement ...

- > Terrain issues Formats, vegetation
- > Soil characterization:
 - Testing at vehicle-scale loads and geometry
 - Simplified terramechanics: theory vs practice
 - Complex terramechanics: characterization, scaling
- > Tire Details soil/obstacle interaction
- ➤ Methods maturity for terramechanics
- To Discuss leveraging MSC technology for your Mobility Requirements:

Eric Pesheck, PhD <u>Eric.Pesheck@mscsoftware.com</u>,

MSC Simulation Services: 734-546-4634



Disclaimer: Reference herein to any specific commercial company, product, process, or service by trade name, trademark, manufacturer, or otherwise, does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or the Department of the Army (DoA). The opinions of the authors expressed herein do not necessarily state or reflect those of the United States Government or the DoA, and shall not be used for advertising or product endorsement purposes.





O - 14 STO-TM-AVT-308